# **NAG Toolbox for MATLAB**

## f08ts

# 1 Purpose

f08ts reduces a complex Hermitian-definite generalized eigenproblem  $Az = \lambda Bz$ ,  $ABz = \lambda z$  or  $BAz = \lambda z$  to the standard form  $Cy = \lambda y$ , where A is a complex Hermitian matrix and B has been factorized by f07gr, using packed storage.

# 2 Syntax

# 3 Description

To reduce the complex Hermitian-definite generalized eigenproblem  $Az = \lambda Bz$ ,  $ABz = \lambda z$  or  $BAz = \lambda z$  to the standard form  $Cy = \lambda y$  using packed storage, f08ts must be preceded by a call to f07gr which computes the Cholesky factorization of B; B must be positive-definite.

The different problem types are specified by the parameter **itype**, as indicated in the table below. The table shows how C is computed by the function, and also how the eigenvectors z of the original problem can be recovered from the eigenvectors of the standard form.

itype	Problem	uplo	В	С	Z
1	$Az = \lambda Bz$	'U' 'L'	$U^{\mathrm{H}}U$ $LL^{\mathrm{H}}$	$U^{-\mathrm{H}}AU^{-1}$ $L^{-1}AL^{-\mathrm{H}}$	$U^{-1}y$ $L^{-H}y$
2	$ABz = \lambda z$	'U' 'L'	$U^{\mathrm{H}}U$ $LL^{\mathrm{H}}$	$UAU^{ m H} \ L^{ m H}AL$	$U^{-1}y$ $L^{-H}y$
3	$BAz = \lambda z$	'U' 'L'	$U^{\mathrm{H}}U$ $LL^{\mathrm{H}}$	$UAU^{\mathrm{H}}$ $L^{\mathrm{H}}AL$	$U^{\mathrm{H}}y$ $Ly$

### 4 References

Golub G H and Van Loan C F 1996 Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

## 5 Parameters

## 5.1 Compulsory Input Parameters

### 1: itype – int32 scalar

Indicates how the standard form is computed.

$$\begin{split} \textbf{itype} &= 1 \\ &\quad \text{if } \textbf{uplo} = \text{'U'}, \ C = U^{-\text{H}} A U^{-1}; \\ &\quad \text{if } \textbf{uplo} = \text{'L'}, \ C = L^{-1} A L^{-\text{H}}. \end{split}$$

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$$\begin{aligned} \textbf{itype} &= 2 \text{ or } 3 \\ &\text{if } \textbf{uplo} = \text{'U'}, \ C = UAU^{\text{H}}; \\ &\text{if } \textbf{uplo} = \text{'L'}, \ C = L^{\text{H}}AL. \\ &\textit{Constraint: } \textbf{itype} = 1, \ 2 \text{ or } 3. \end{aligned}$$

#### 2: **uplo – string**

Indicates whether the upper or lower triangular part of A is stored and how B has been factorized.

$$uplo = 'U'$$

The upper triangular part of A is stored and  $B = U^{H}U$ .

$$uplo = 'L'$$

The lower triangular part of A is stored and  $B = LL^{H}$ .

Constraint: uplo = 'U' or 'L'.

#### 3: n - int32 scalar

n, the order of the matrices A and B.

Constraint:  $\mathbf{n} \geq 0$ .

#### 4: ap(\*) – complex array

**Note**: the dimension of the array **ap** must be at least  $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$ .

The n by n Hermitian matrix A, packed by columns.

More precisely,

if **uplo** = 'U', the upper triangle of A must be stored with element  $A_{ij}$  in  $\mathbf{ap}(i+j(j-1)/2)$  for  $i \le j$ ;

if **uplo** = 'L', the lower triangle of A must be stored with element  $A_{ij}$  in  $\mathbf{ap}(i+(2n-j)(j-1)/2)$  for  $i \ge j$ .

## 5: bp(\*) - complex array

**Note**: the dimension of the array **bp** must be at least  $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$ .

The Cholesky factor of B as specified by **uplo** and returned by f07gr.

### 5.2 Optional Input Parameters

None.

## 5.3 Input Parameters Omitted from the MATLAB Interface

None.

### 5.4 Output Parameters

### 1: ap(\*) – complex array

**Note**: the dimension of the array **ap** must be at least  $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$ .

The upper or lower triangle of ap contains the corresponding upper or lower triangle of C as specified by **itype** and **uplo**, using the same packed storage format as described above.

### 2: info – int32 scalar

info = 0 unless the function detects an error (see Section 6).

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# 6 Error Indicators and Warnings

Errors or warnings detected by the function:

```
info = -i
```

If info = -i, parameter i had an illegal value on entry. The parameters are numbered as follows: 1: itype, 2: uplo, 3: n, 4: ap, 5: bp, 6: info.

## 7 Accuracy

Forming the reduced matrix C is a stable procedure. However it involves implicit multiplication by  $B^{-1}$  if (**itype** = 1) or B (if **itype** = 2 or 3). When f08ts is used as a step in the computation of eigenvalues and eigenvectors of the original problem, there may be a significant loss of accuracy if B is ill-conditioned with respect to inversion. See the document for f08sn for further details.

#### **8** Further Comments

The total number of real floating-point operations is approximately  $4n^3$ .

The real analogue of this function is f08te.

# 9 Example

```
itype = int32(1);
uplo = 'L';
n = int32(4);
ap = [complex(-7.36, +0);
     complex(0.77, +0.43);
     complex(-0.64, +0.92);
     complex(3.01, +6.97);
     complex(3.49, +0);
     complex(2.19, -4.45);
complex(1.9, -3.73);
     complex(0.12, +0);
     complex(2.88, +3.17);
     complex(-2.54, +0)];
bp = [complex(1.797220075561143, +0);
     complex(0.8401864749527325, +1.068316577423342);
     complex(1.057188279741849, -0.467388502622712);
     complex(0.233694251311356, -1.391037210186643);
     complex(1.316353439509685, +0);
     complex(-0.4701749470106329, +0.3130658155999466);
     complex(0.08335250923944192, +0.03676071443037458);
     complex(1.560392977137124, +0);
     complex(0.9359617337923402, +0.9899692192815736);
     complex(0.6603332973655893, +0)];
[apOut, info] = f08ts(itype, uplo, n, ap, bp)
apOut =
  -2.2786
   1.7799 + 2.0310i
   2.2594 - 0.0996i
  -0.1206 - 2.5286i
  -1.1255
  0.0090 - 0.4261i
  -1.0602 - 0.8600i
  -0.3715
  2.3103 + 0.9198i
  -0.7133
info =
           0
```

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